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Cable Damage Detection Algorithms for Time Domain Reflectometry Signals

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Livermore, CA, United States
November 20, 2008 through November 21, 2008

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Signal and Imaging Sciences Workshop, Center for Advanced Signal and Image Sciences, Lawrence Livermore
National Laboratory, November 20-21, 2008

Cable Damage Detection Algorithms for Time Domain Reflectometry Signals

November 20-21, 2008



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Eng/NSED/Systems and Intelligence Analysis Section

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We Have an Interdisciplinary Team

- **Graham Thomas - ENG/MMED**
 - Project Management
 - NDE, materials characterization
- **Chris Robbins - ENG/NSED**
 - Program Management
 - Data acquisition, hardware, signal processing software, NDE
- **Grace Clark - ENG/NSED**
 - Image/signal processing, target/pattern recognition, sensor data fusion, NDE
- **Katherine Wade - ENG/NSED**
 - Signal processing software and testing
- **Paul Sousa - ENG**
 - Laboratory technician, data acquisition



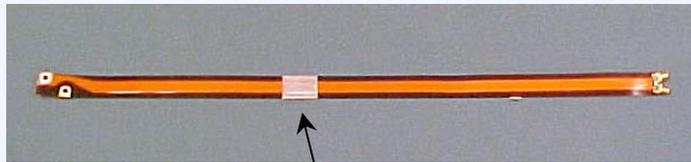
Agenda

- **Introduction**
 - **The Cable Damage Detection Problem**
 - **This is work in progress**
- **Technical Approach - *Model-Based Damage Detection***
- **Damage Detection Processing Results**
 - **Real Measurements, Artificial Damage - *Reported Earlier***
 - **Real measurements, real damage**
 - **Performance Measurements**
 - ***ROC Curves, Confidence Intervals***
- **Discussion and Plans**

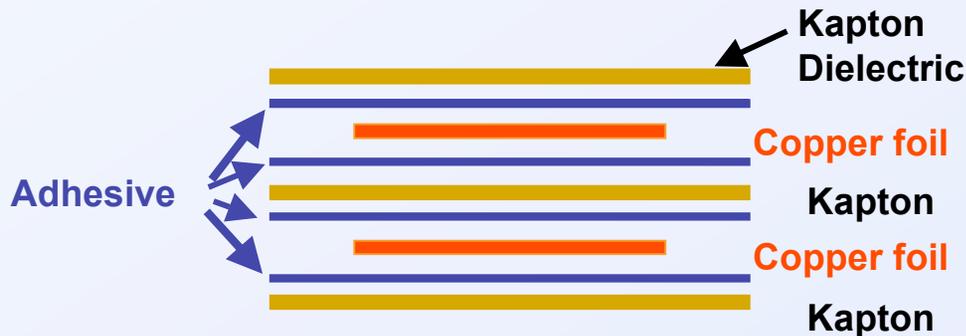


We Are Testing Two-Conductor Flat Cables With Kapton Insulation - For Dielectric Anomalies

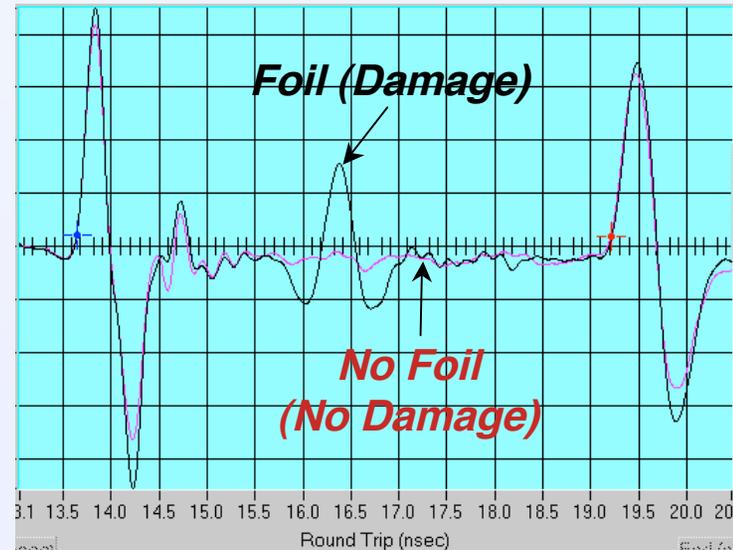
Two-Conductor Flat Cable With Kapton Insulation



Foil Simulating a Capacitive Discontinuity (Damage)



Red TDR Signal => Good Cable
Black TDR Signal => Damaged Cable



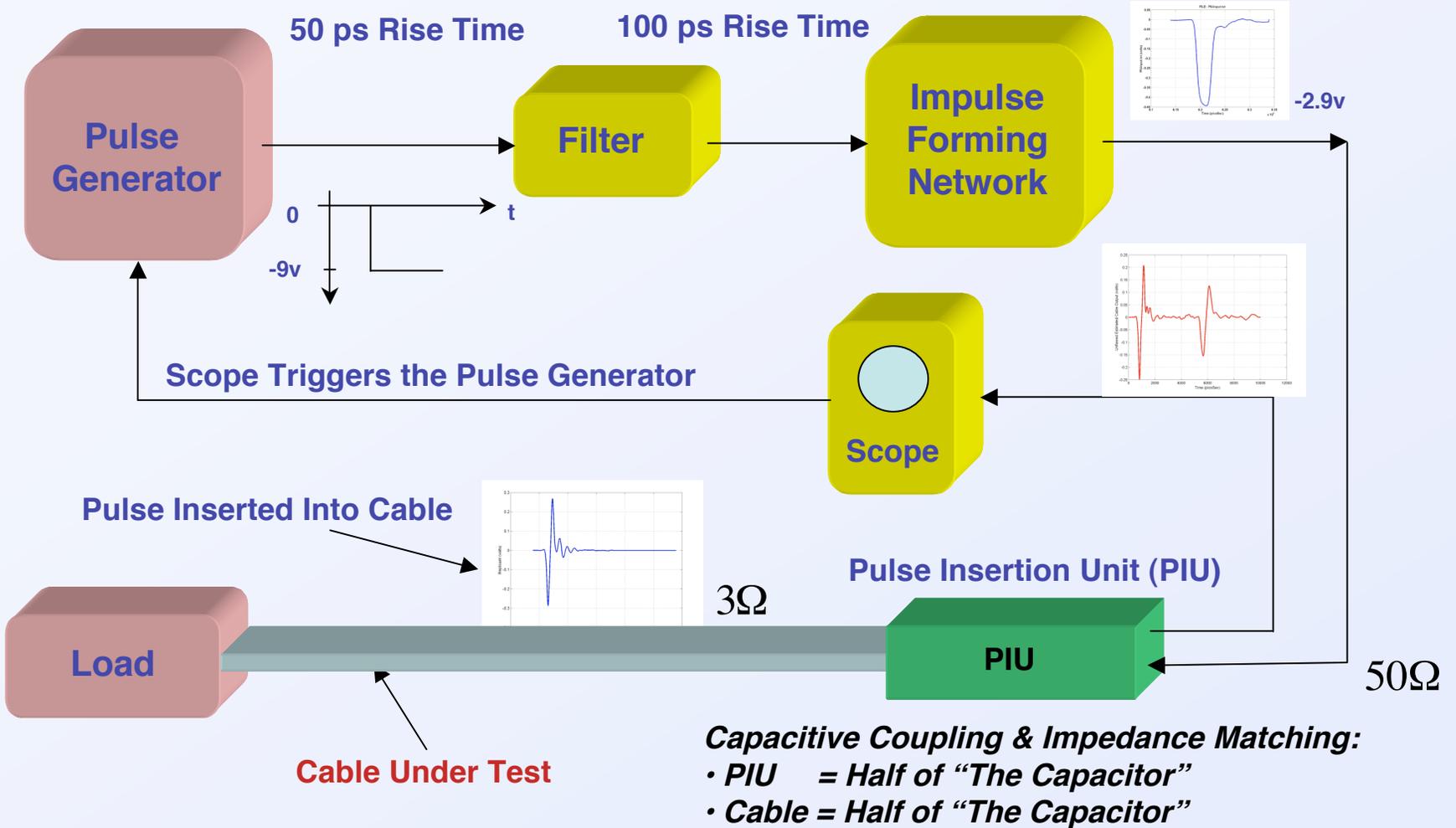
Expected Damage Types:

- *Compressions*
- *Punctures*
- *Short Circuits*
- *Open Circuits*



The Key Hardware Component is the *Pulse Insertion Unit (PIU)*

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The Technical Challenges/Issues are Difficult, But We Do Not Know Yet *Exactly How Difficult*

- We have access to only one end of the cable
- We cannot “Hi-Pot” the cables in place
- We have no exemplars of “real” damaged cables
 - We must “insult” them artificially
- We have no archive signals from the cables “As-Built”
 - Only a “typical” signal for an undamaged cable
- Small sample size
 - Small number of available cables for “insulting” (~ 60)
 - Obviates using supervised learning pattern recognition algorithms
 - Makes it difficult to create ensembles for building ROC curves
- Repeatability of Measurements (***A VERY IMPORTANT ISSUE***)
 - Single cable - Test to test [*Apparently solved to first order*]
 - Cable to cable [*Solved after lots of hard work*]
- The signal shape changes significantly with the cable environment
 - We have 2D and 3D “Mockups”



Repeatability: Use a Confidence Interval About the Mean

[Small Sample Size Case ($M < 30$)]

If the *test statistic* $\mu(t)$ is Gaussian distributed, then the **95% confidence interval** estimate of the test statistic for small *sample size* ($M < 30$) is:

$$P\left\{\bar{z}(t) - \frac{bS(t)}{\sqrt{M-1}} < \mu(t) < \bar{z}(t) + \frac{bS(t)}{\sqrt{M-1}}\right\} = 1 - \alpha = .95$$

$\alpha = \text{Significance Level} = .05$

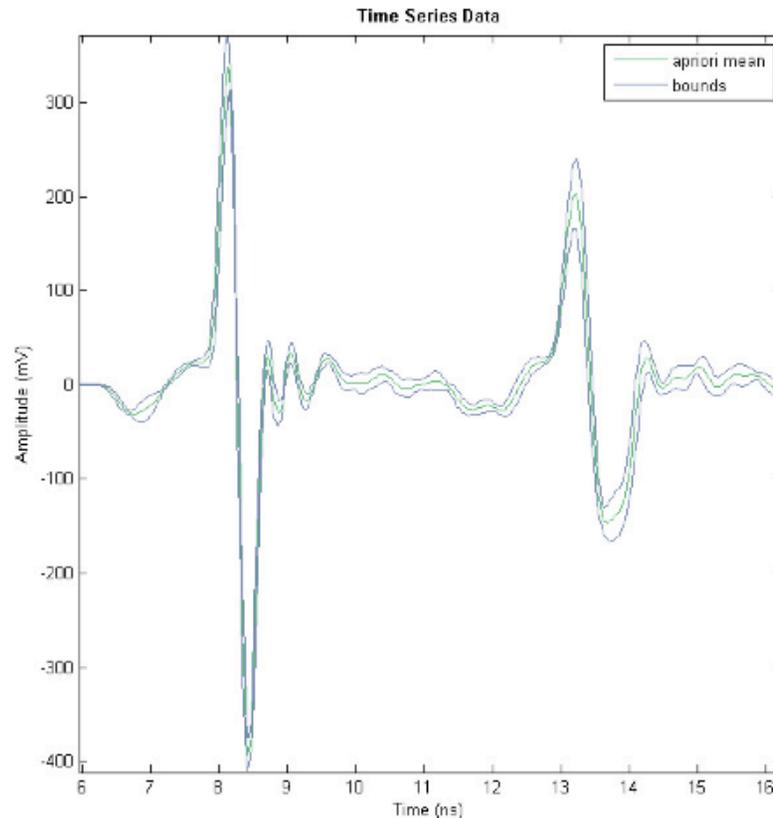
“With confidence 95%, the test statistic lies between the lower bound and the upper bound.”

Note: For this case, we must use the Student’s t distribution to compute the bounds.

Note: b is a constant that depends on the sample size M. For $M < 30$, choose b from a “Student’s t table.”



We Plot the Ensemble Sample Mean Signal and its Confidence Interval Bounds about the Mean

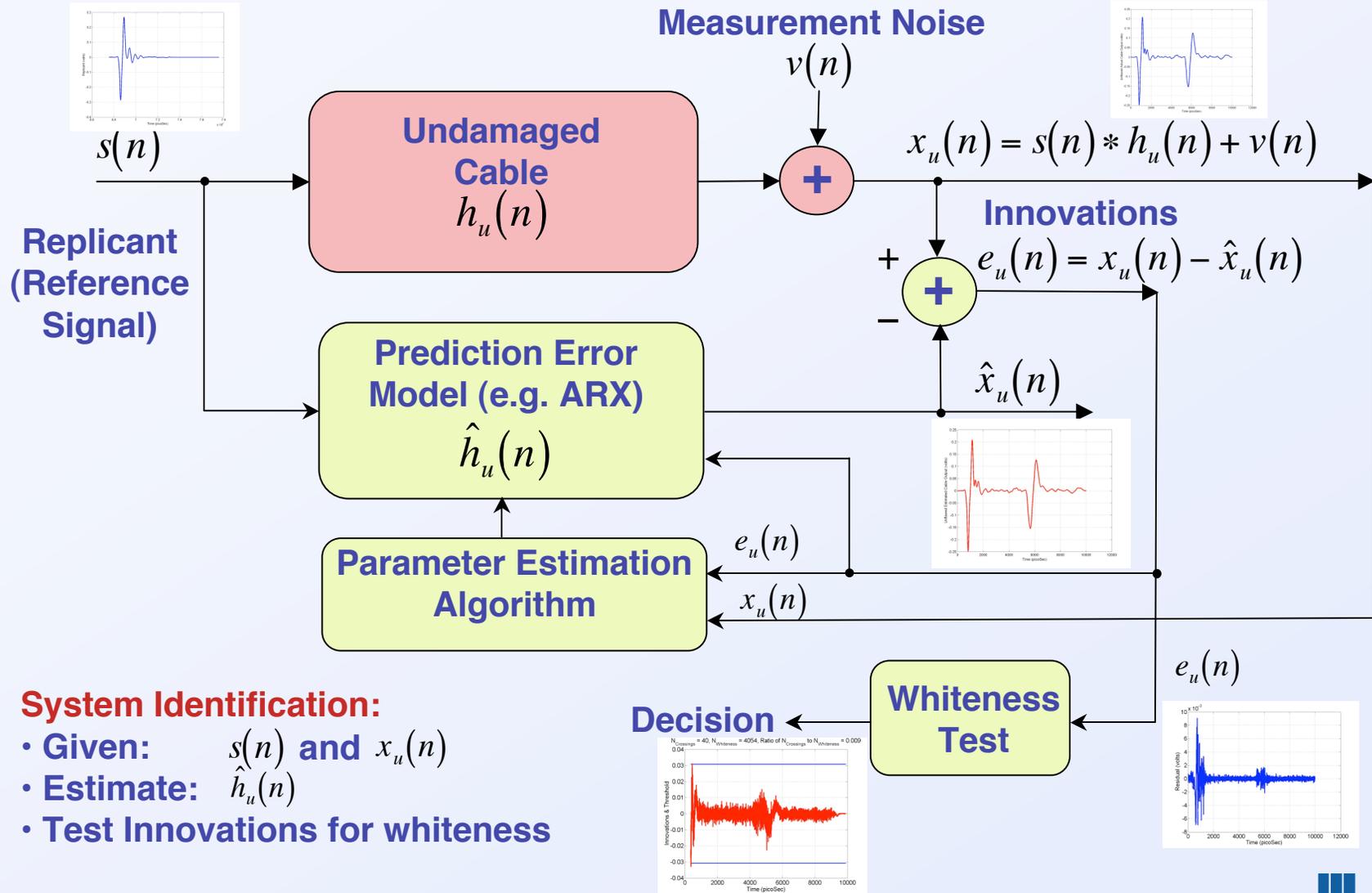


- Let F = Fraction of samples of mean that exceed the threshold
- If $F \leq \alpha$, Declare *Signal Ensemble is repeatable*
- If $F > \alpha$, Declare *Signal Ensemble is not repeatable*



Step #1: System Identification to Estimate the Dynamic Model of the *Undamaged Cable*

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System Identification:

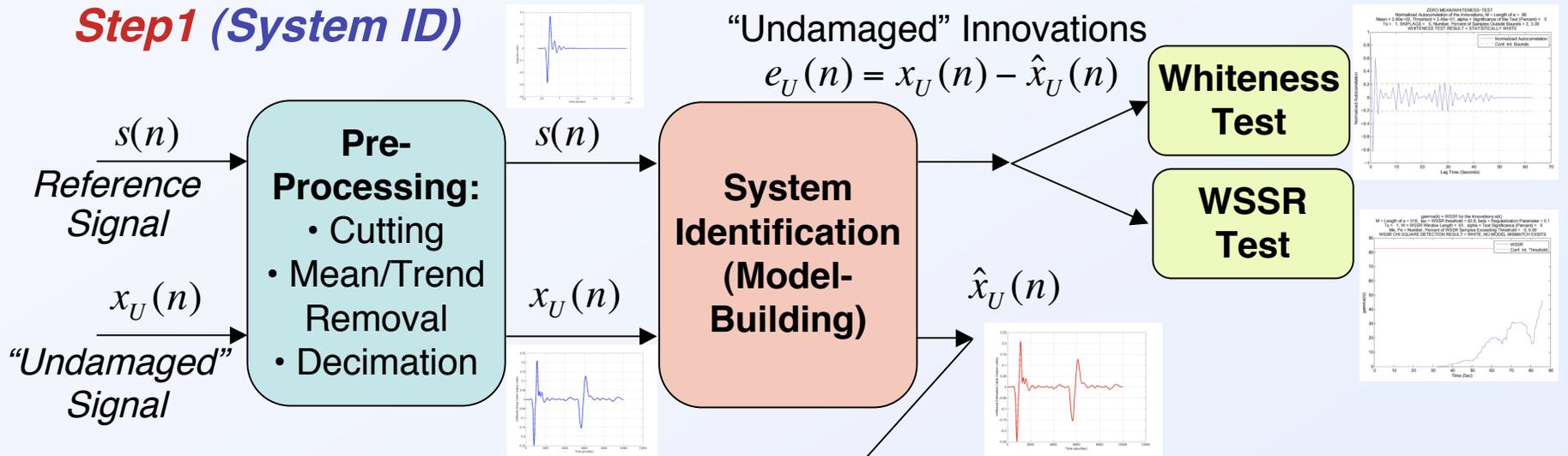
- **Given:** $s(n)$ and $x_u(n)$
- **Estimate:** $\hat{h}_u(n)$
- **Test Innovations for whiteness**



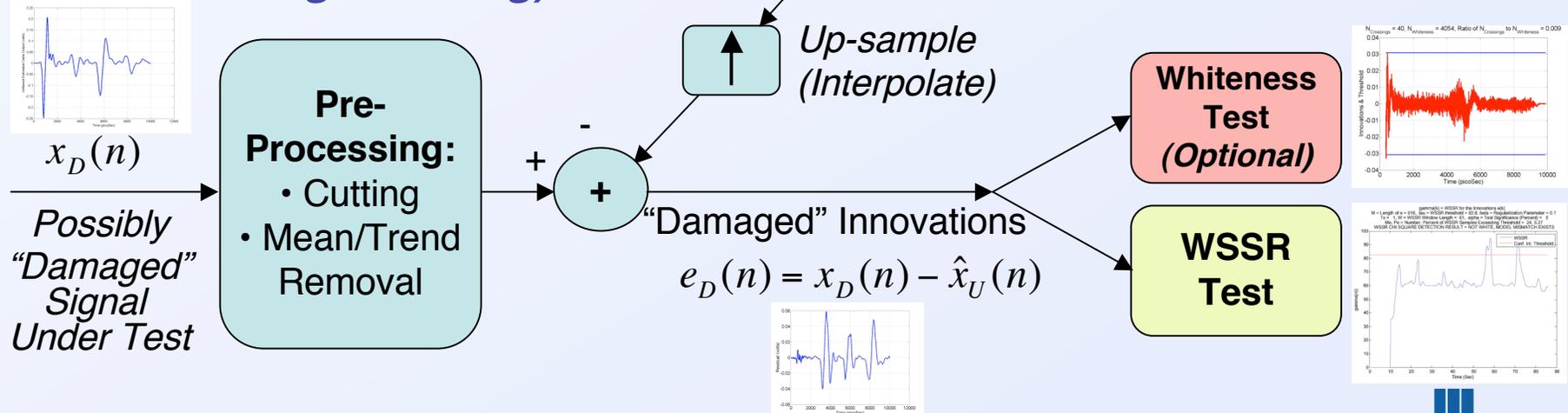
Step1 (System ID) is Done “Offline”

Step2 (Damage Testing) is Done “Online”

Step1 (System ID)



Step2 (Damage Testing)



The Form of the Linear System Model Used is “ARX” = “Auto-Regressive with Exogenous Input”

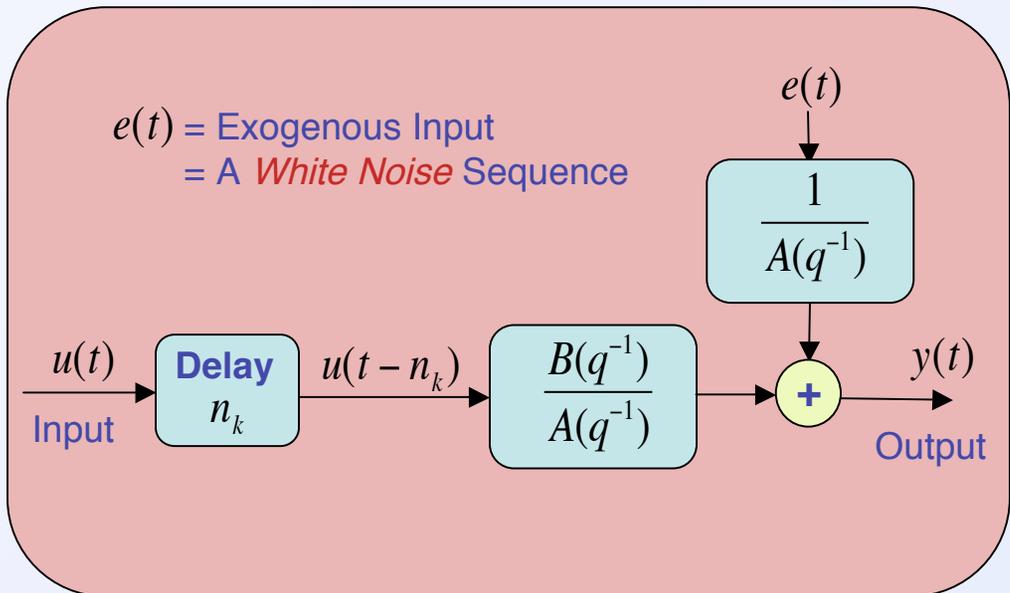
$$y(t) = \frac{B(q^{-1})}{A(q^{-1})} u(t - nk) + \frac{1}{A(q^{-1})} e(t)$$

Where:

$$A(q) = 1 + a_1 q^{-1} + a_2 q^{-2} \cdots + a_{N_a} q^{-N_a}$$

$$B(q) = b_0 + b_1 q^{-1} + b_2 q^{-2} \cdots + b_{N_b} q^{-N_b}$$

q^{-1} = Delay Operator



The model parameters are estimated using a least squares algorithm:

- Solve an over-determined set of linear equations
- Solve using QR factorization algorithm
- The regression matrix is formed so that only measured quantities are used (no fill-out with zeros).



Scalar WSSR (Weighted Sum Squared Residuals) Test

For a Scalar Measurement ($p = 1$)

Given the innovations signal $e(n)$

We define the scalar WSSR test statistic at time index n :

$$\gamma(n) = \sum_{j=n-W+1}^n \frac{e^2(j)}{V(j)}, \quad \text{for } n \geq W$$

Note: We estimate WSSR over a finite sliding window of length W samples.

Where:

$$V(n) = \frac{1}{W} \sum_{j=n-W+1}^n [e^2(j) - \bar{e}(j)]^2, \quad \text{for } n \geq W$$

Sample variance
over the sliding window

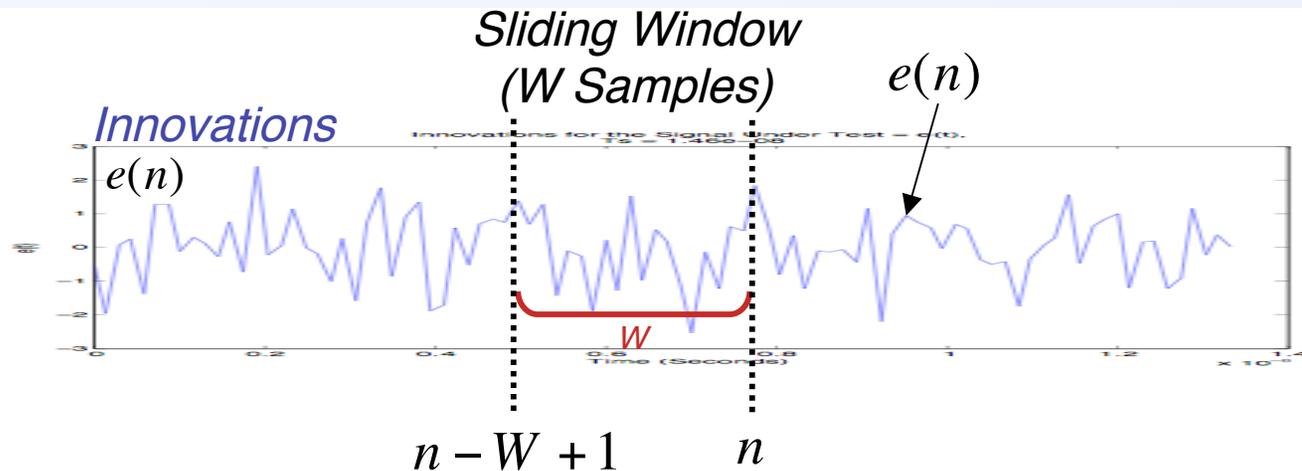
$$\bar{e}(n) = \frac{1}{W} \sum_{j=n-W+1}^n e(j), \quad \text{for } n \geq W$$

Sample mean
over the sliding window



Scalar WSSR is Calculated Using a Sliding Window Over the Innovations Sequence $e(n)$

WSSR = “Weighted Sum Squared Residuals”



$$\gamma(n) = \sum_{j=n-W+1}^n \frac{e^2(j)}{V(j)}, \quad \text{for } n \geq W$$

WSSR is a useful test statistic for detecting an abrupt change, or “jump” in the innovations



The Scalar WSSR Confidence Interval Threshold is Parameterized by *the Window Length W*

Summary of the WSSR Test for Significance $\alpha = .05$:

$$\gamma(n) = \sum_{j=n-W+1}^n \frac{e^2(j)}{V(j)}, \quad \text{for } n \geq W$$

$$V(n) = \frac{1}{W} \sum_{j=n-W+1}^n [e^2(j) - \bar{e}(j)]^2, \quad \text{for } n \geq W$$

$$\bar{e}(n) = \frac{1}{W} \sum_{j=n-W+1}^n e(j), \quad \text{for } n \geq W$$

$$\tau = W + 1.96\sqrt{2W}$$

$$\text{If } \gamma(n) \begin{matrix} \geq H_1 \\ < H_0 \end{matrix} \tau, \quad (\tau = \text{Decision Threshold})$$

In practice, we implement the WSSR test as follows:

- Let F_E = Fraction of samples of $\gamma(n)$ that exceed the threshold
- If $F_E \leq \alpha$, Declare H_0 is true (innovations are white, no jump)
- If $F_E > \alpha$, Declare H_1 is true (innovations are not white, jump)



We Acquired an Ensemble of Real Signals for Processing

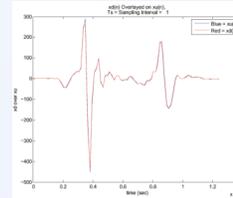
The PIU was never disconnected between acquisitions

Experiment E1: Data from 2_13_07

UNDAMAGED

Reference Signals (*Undamaged*):

refa, refb, refc



MINOR DAMAGE

Minor Damage (*pin hole, knife present, no short*):

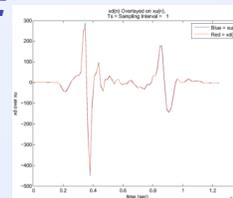
minor1a, minor1b, minor1c

Minor Damage (*pin hole, knife removed, no short*):

minor2a, minor2b, minor2c

Minor Damage (*pin hole, knife removed, cable rubbed to remove short*):

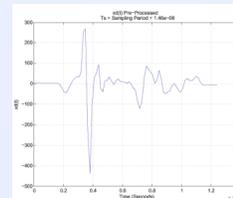
minor3a, minor3b, minor3c



MAJOR DAMAGE

Major Damage (*pin hole, knife removed, conductors shorted*):

major1a, major1b, major1c



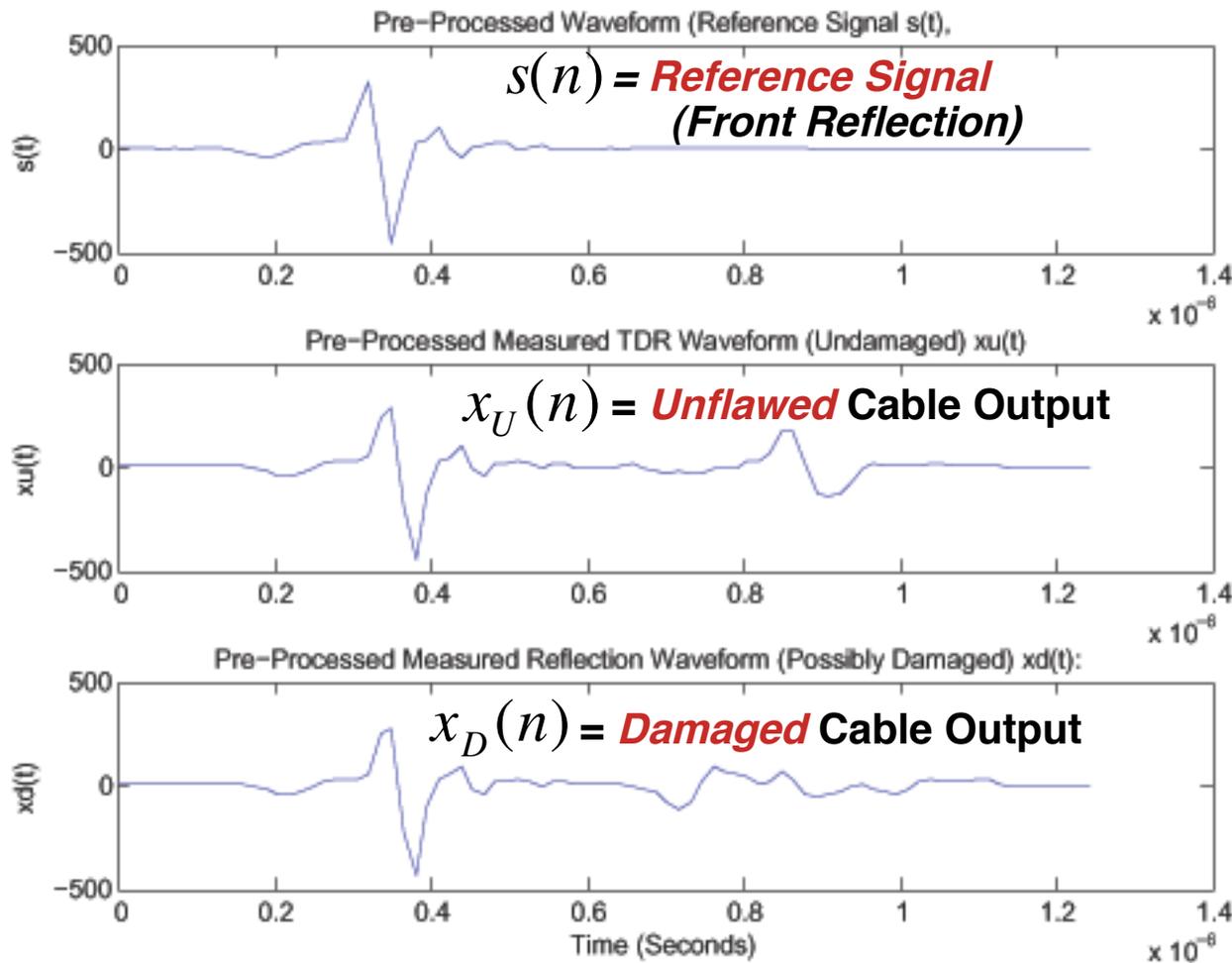
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Experiment 1: System Identification Results



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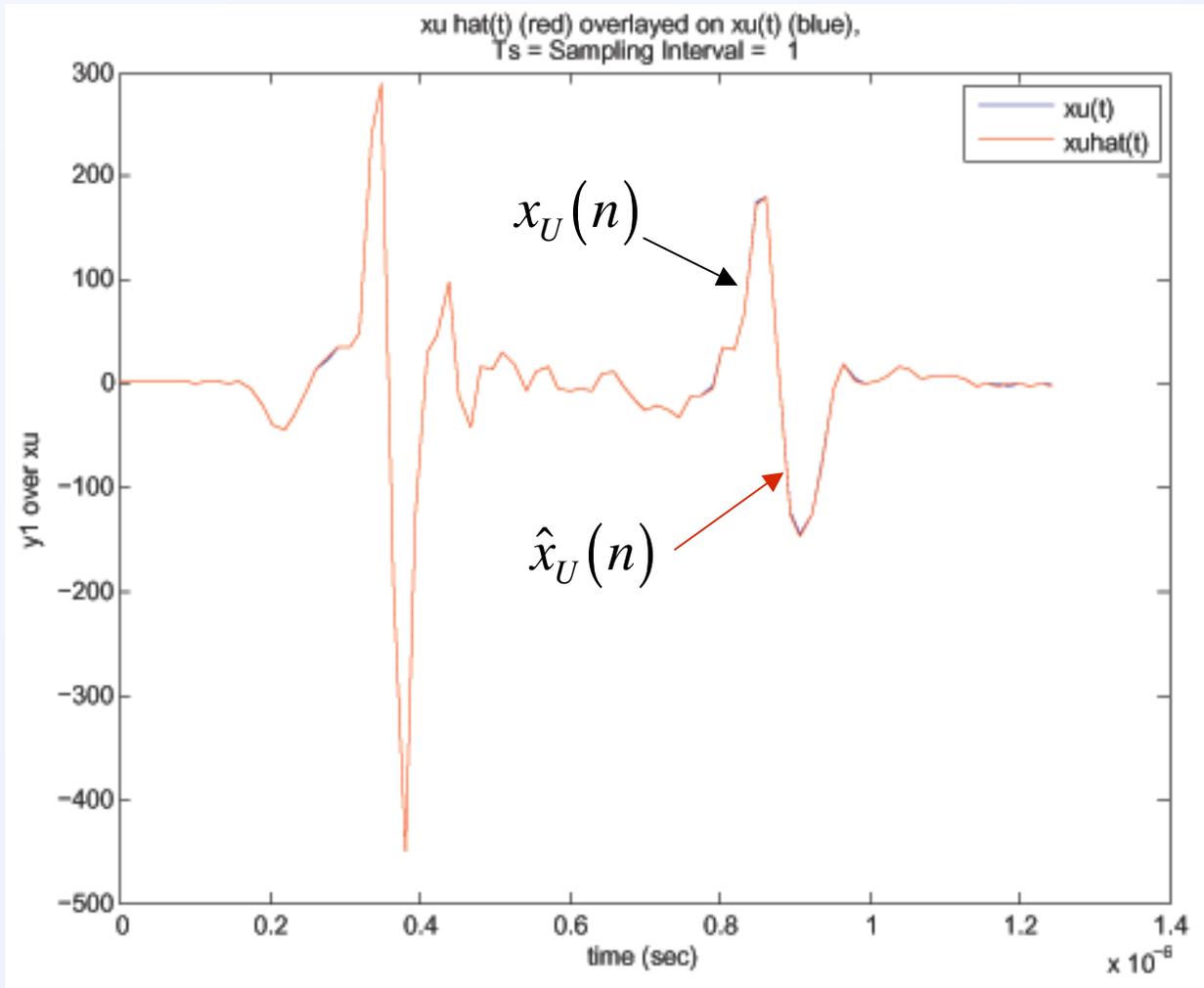
System Identification: Preprocessed Signals



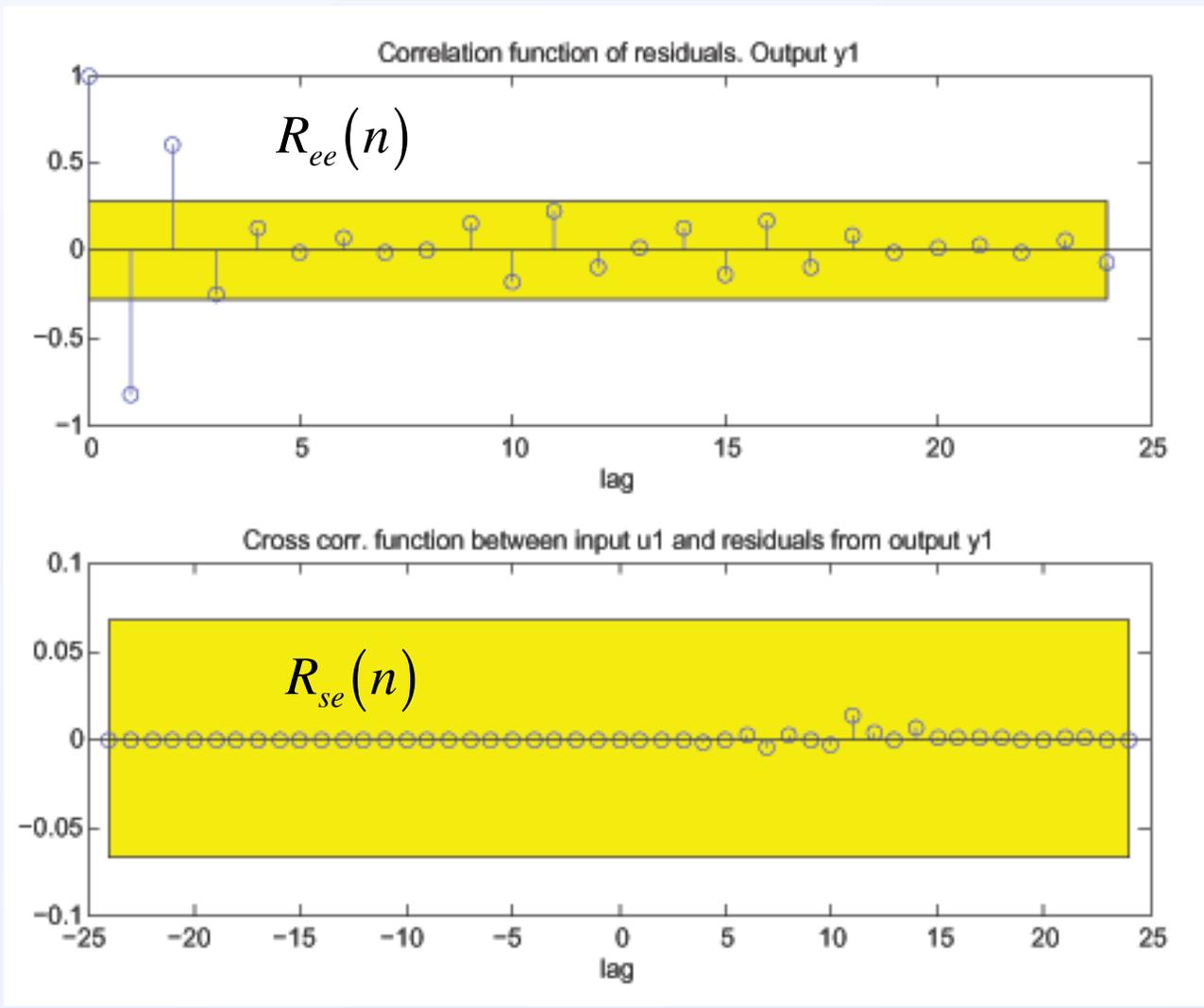
**Example:
Major
Damage**



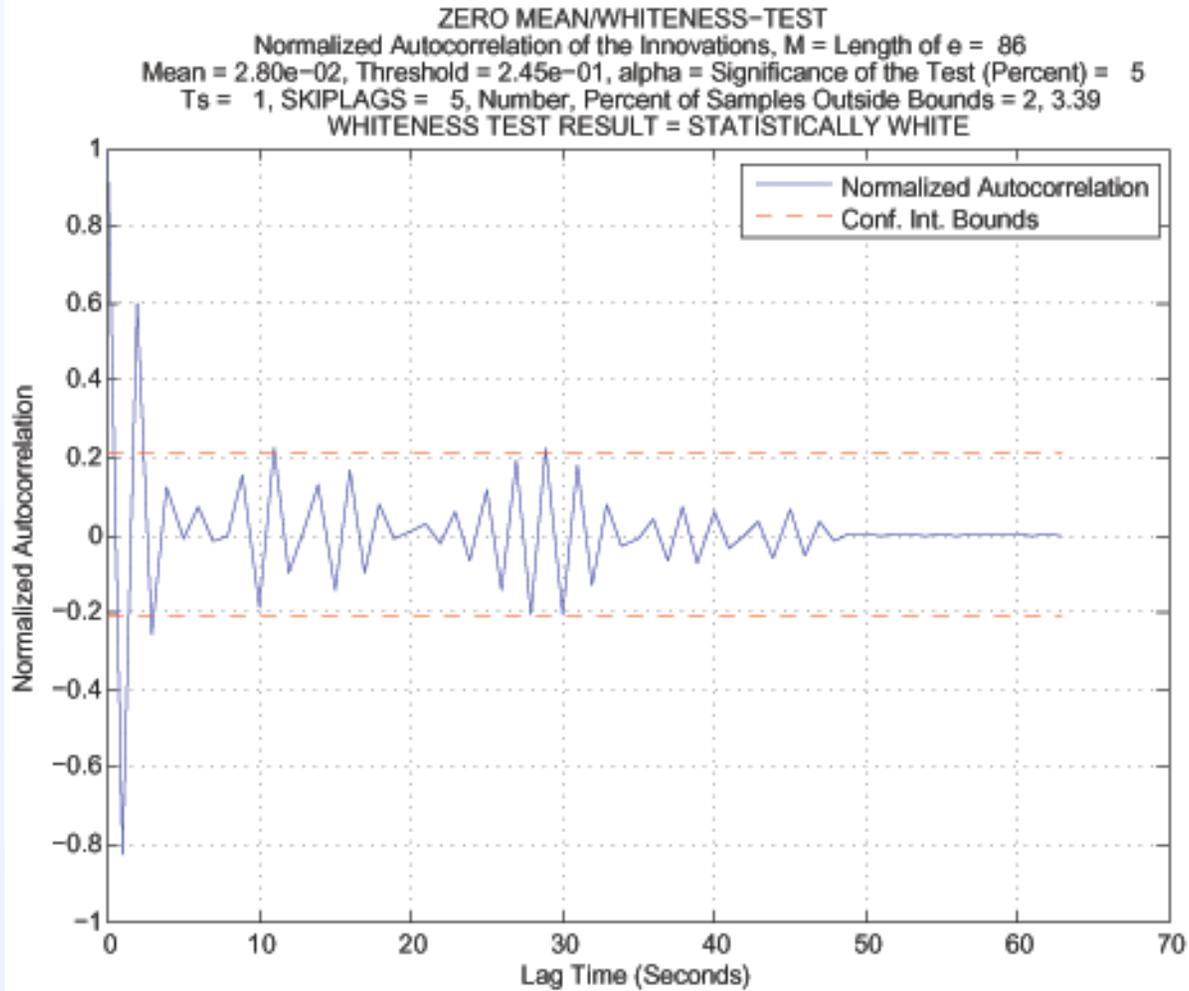
System Identification: *The Model Fit is Good*



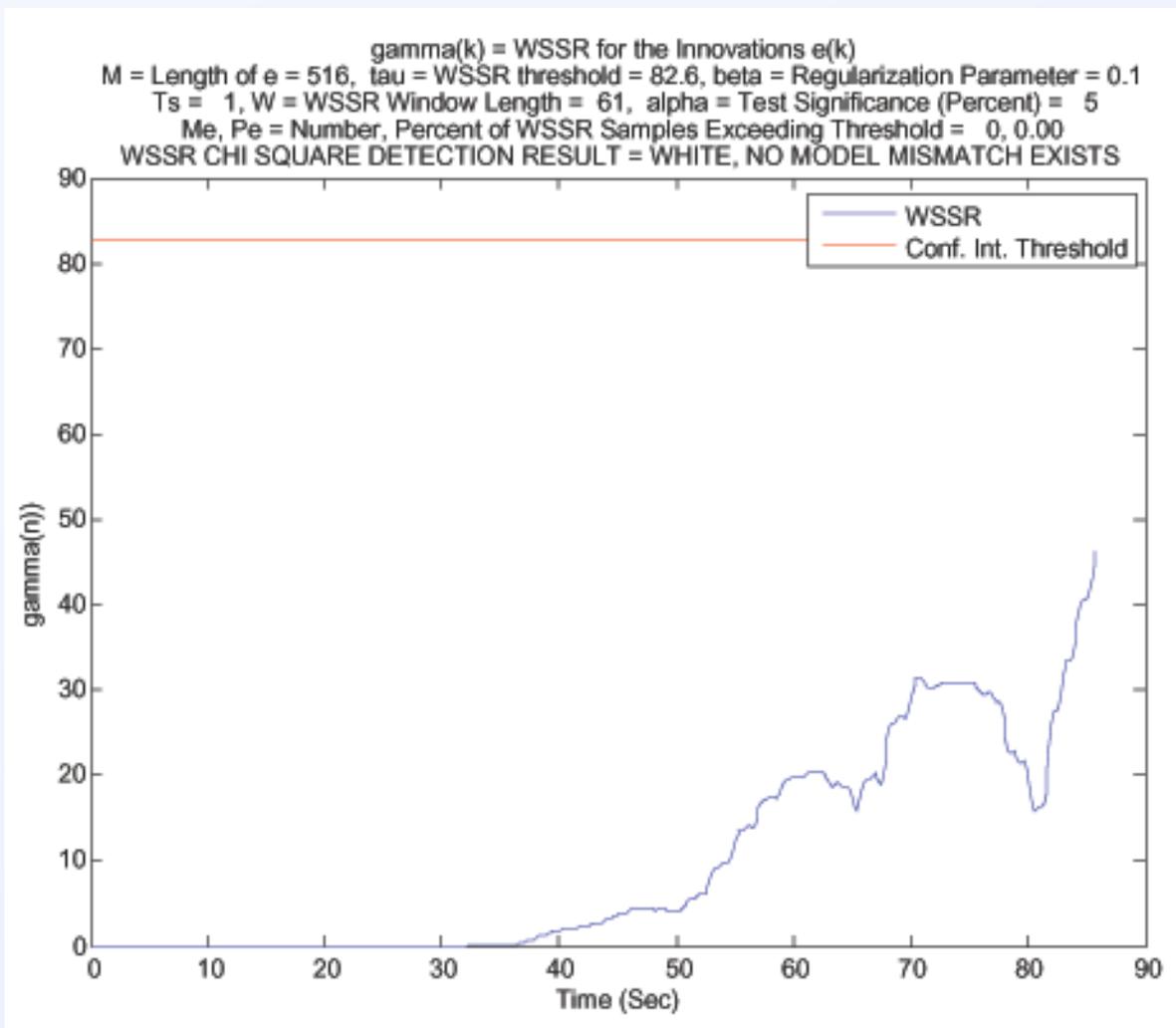
System Identification: *Correlation Tests are Satisfactory*



System Identification Whiteness Test Result = *White*



System Identification WSSR Test Result = *No Model Mismatch!*



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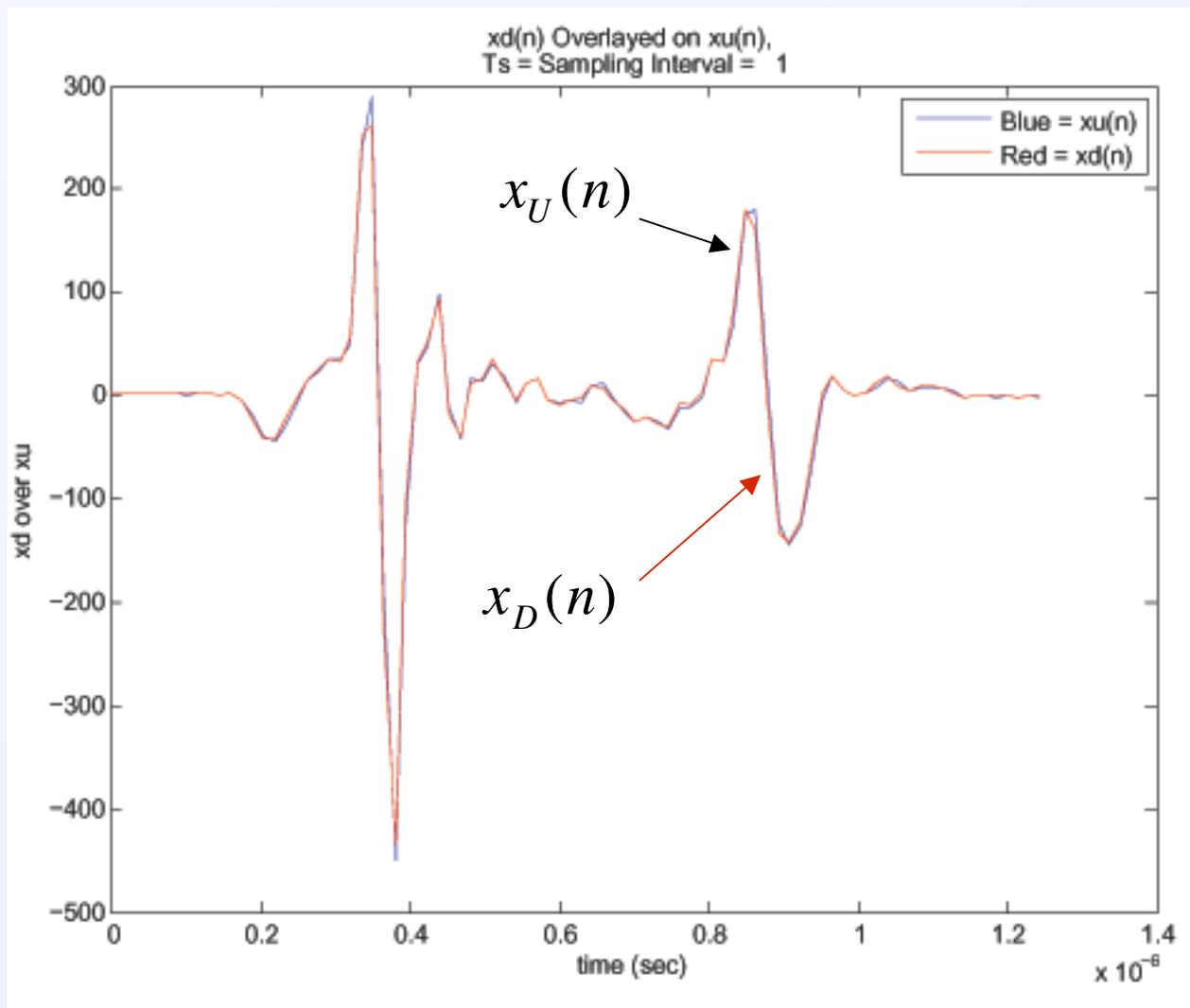
Experiment 1:
“Minor3” Damage



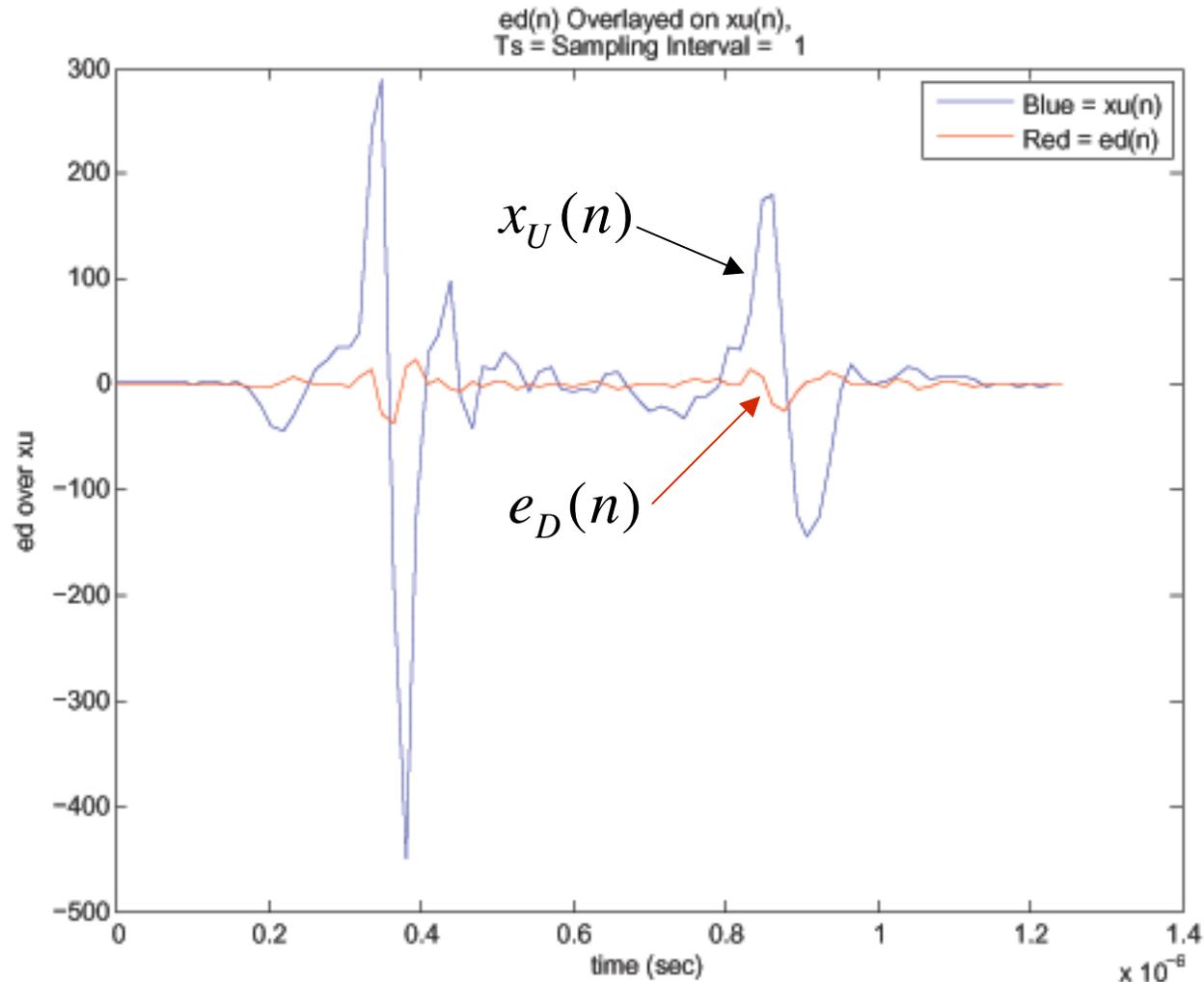
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E1_xd_m3a_xuC.pdf

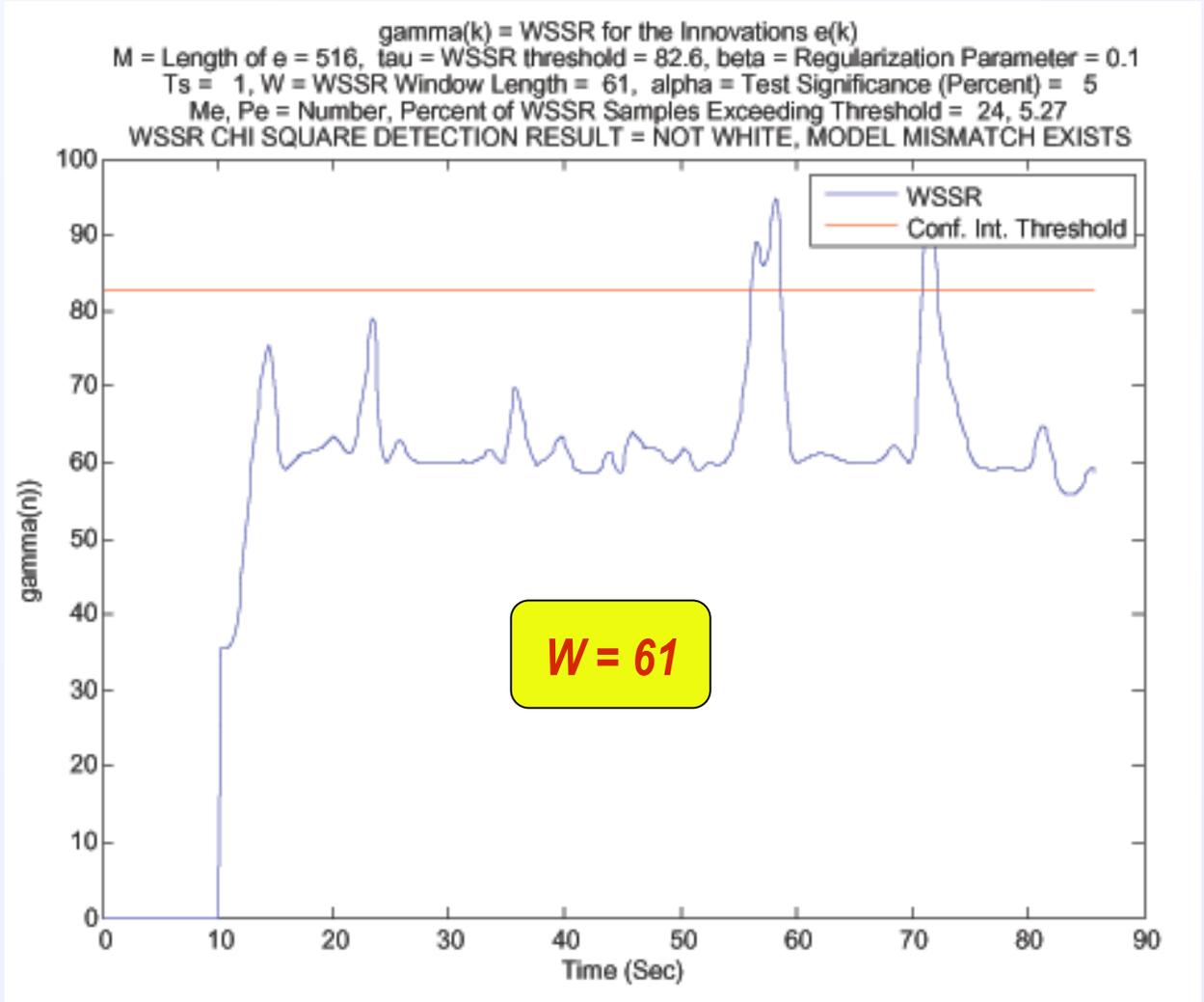
“Minor3 Damage”: *Damage Is Difficult to Distinguish Visually*



Minor3 Damage: *The Innovations are Small, But Correlated*



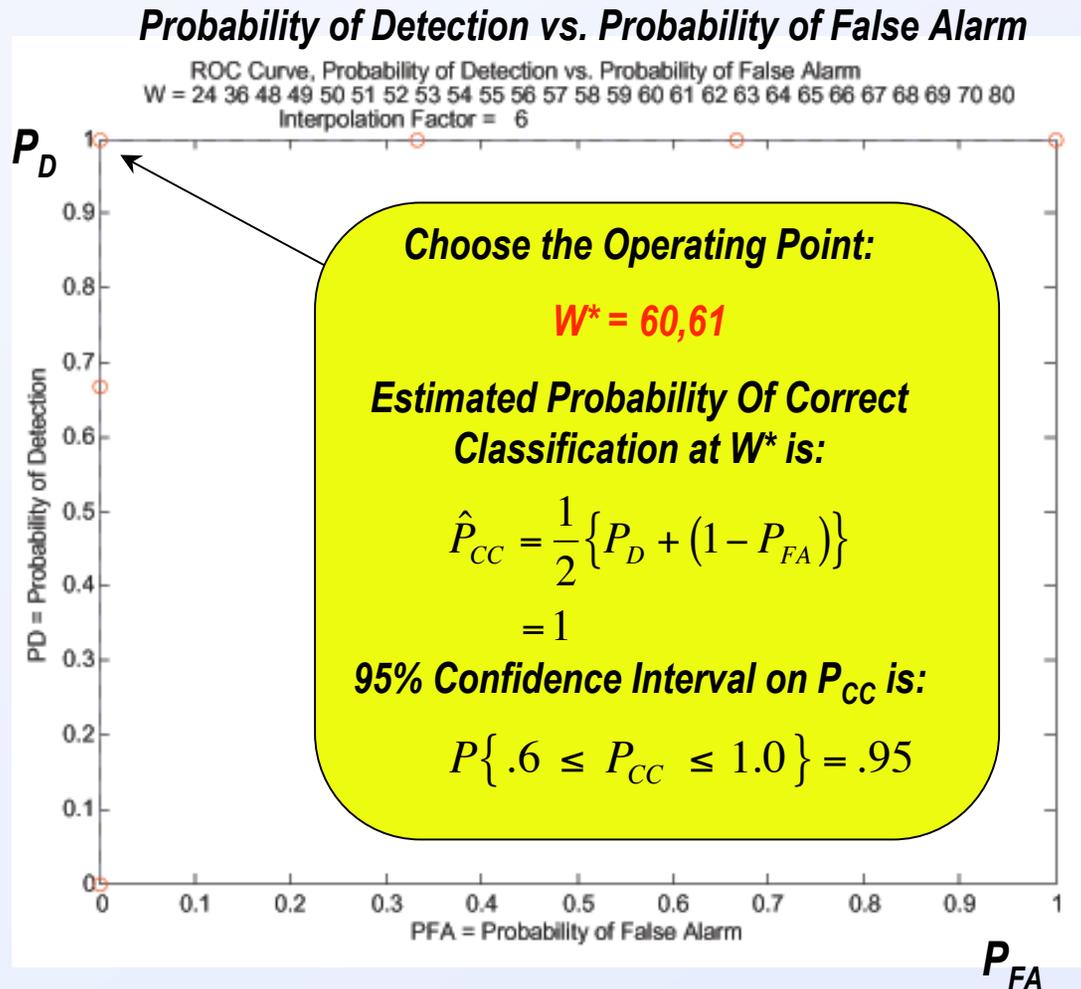
“Minor3 Damage” WSSR Result = *Model Mismatch!*



Minor3a,b,c Damage

Receiver Operating Characteristic (ROC) Curve = *Ideal*

W	P_{FA}	P_D
24	1	1
36	0.66667	1
48	0.66667	1
49	0.66667	1
50	0.66667	1
51	0.66667	1
52	0.66667	1
53	0.66667	1
54	0.66667	1
55	0.66667	1
56	0.33333	1
57	0.33333	1
58	0.33333	1
59	0.33333	1
60	0	1
61	0	1
62	0	0.66667
70	0	0
80	0	0



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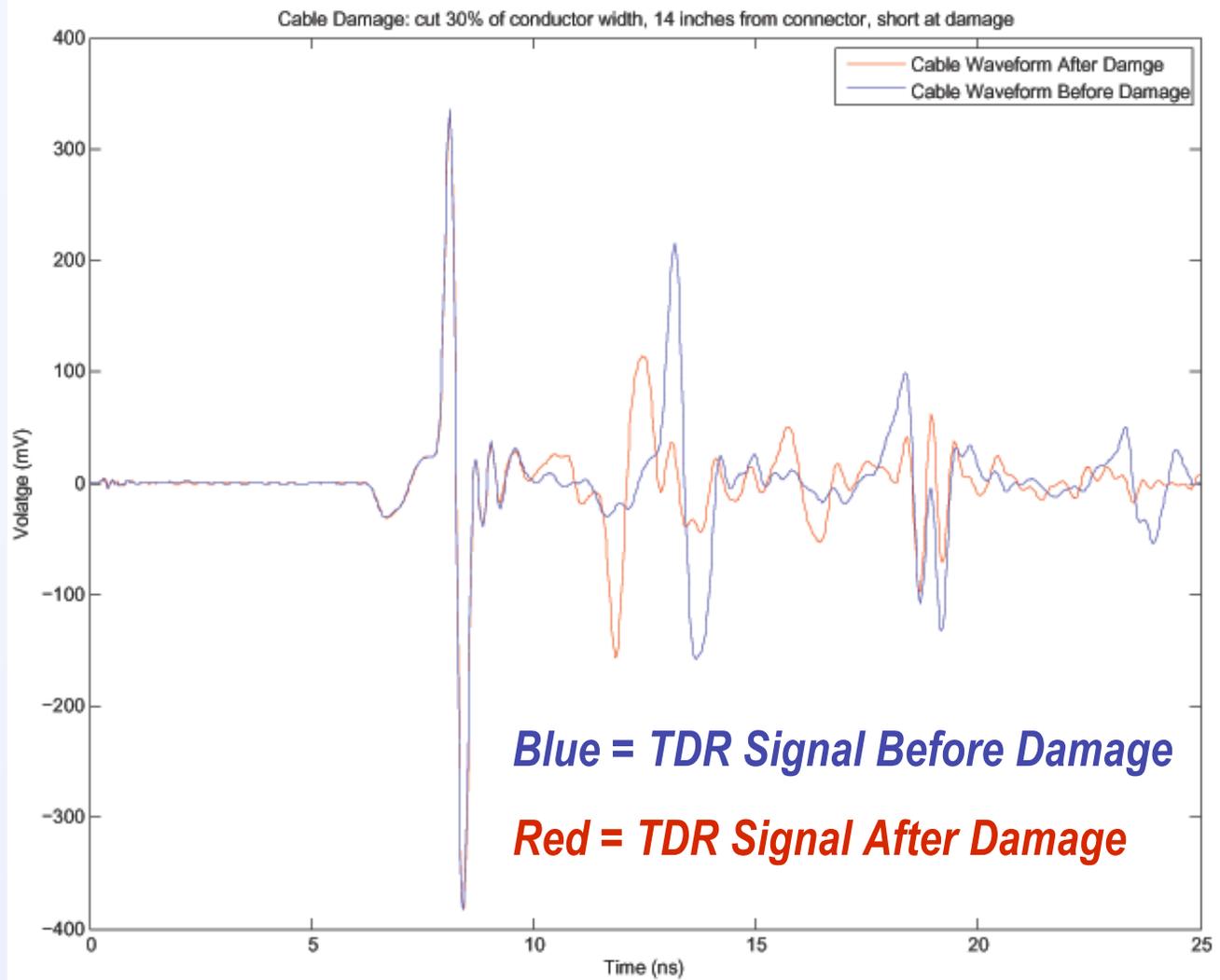
Experiment 5b: Obvious Damage



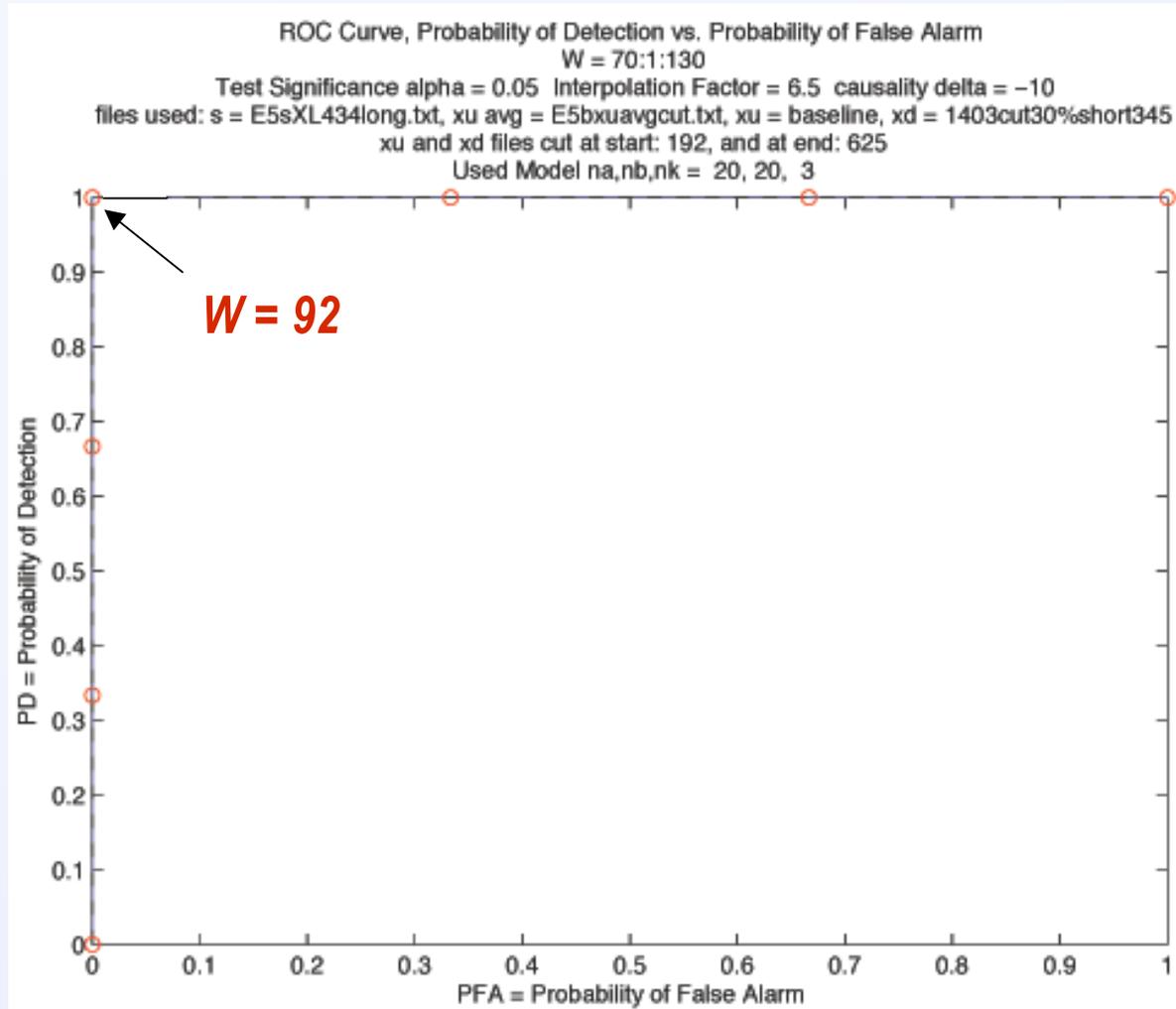
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Exp. (1)E5b: Obvious Damage

Cut 30% of Conductor Width, 14 in from connector, cable shorted

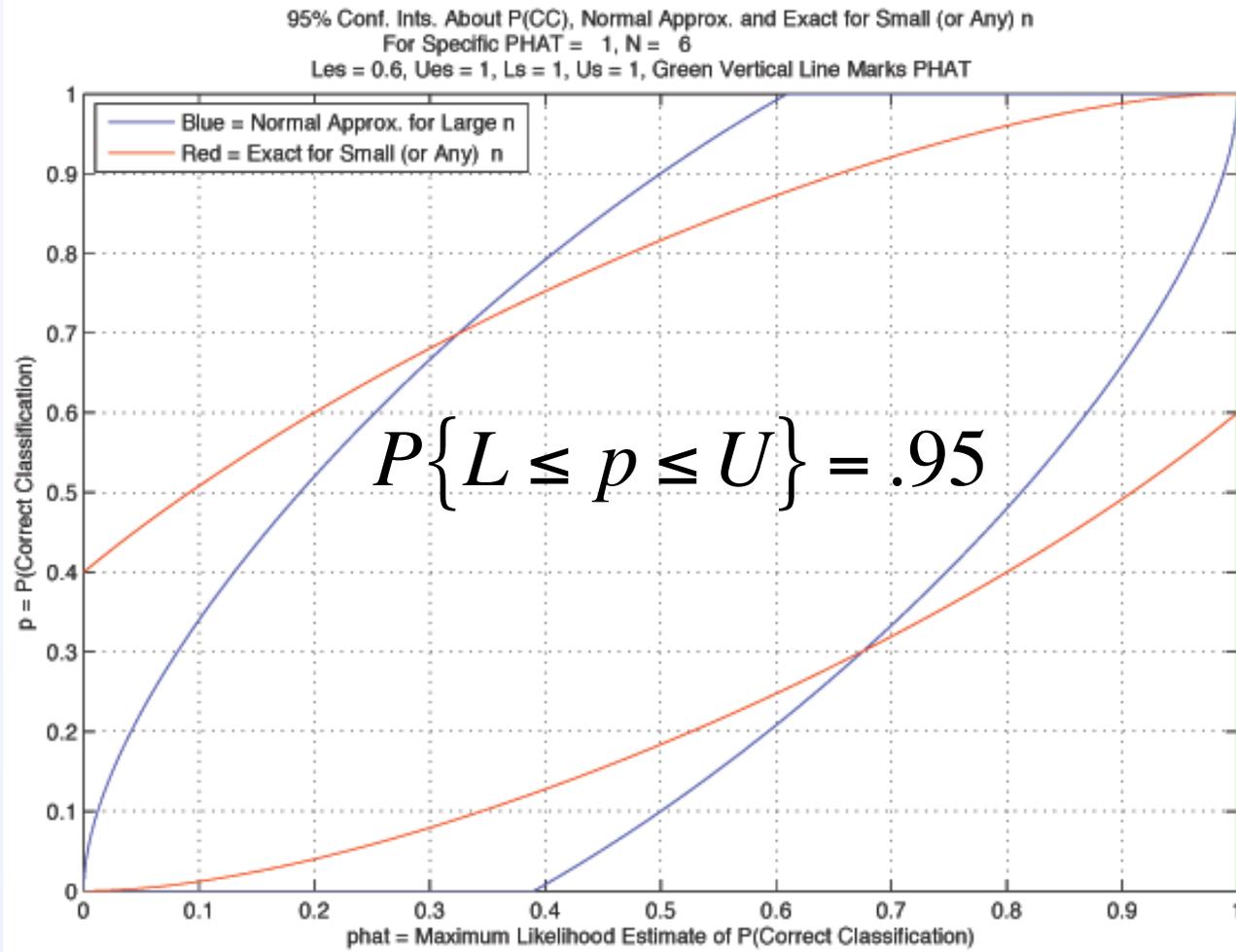


Exp. (1)E5b: Obvious Damage, ROC Curve is Ideal
Cut 30% of Conductor Width, 14 in from connector, cable shorted



Exp. (1)E5b: Obvious Damage, Confidence Interval on P(CC)
Cut 30% of Conductor Width, 14 in from connector, cable shorted

True P(CC) from Theory



Upper Bound
 U = 1

Lower Bound
 L = .6

$\hat{p} = 1$

Estimated P(CC) from Contingency Table



Conclusions & Future Work

- **Tests with real data validate the algorithms:**
 - *Earlier tests with cables on a work bench*
 - *Cable not removed between measurements*
 - *Recent tests with cables in the 2D mockup fixture*
 - *Cable removed between measurements*
 - *Can sometimes detect damage that is not obvious by visual inspection*
- **The most difficult issues have been:**
 - *Repeatability of the TDR measurements in the 2D fixture*
Extensive work was required to achieve repeatability

Future Work:

- *Cable “Insult Studies” with more damage types*
- *Tune the adjustable algorithm parameters for best performance*
 - *Interpolation factors, significance of tests, etc.*
- *Experiments in realistic cable environments - 3D Mockup*
- *Use algorithms with other applications - Other systems, optical cables*

